



# THE MAKERSPACE

---

Cooper Union Summer STEM 2015

Prof. Victoria Bill

Prof. Yosef Skolnick



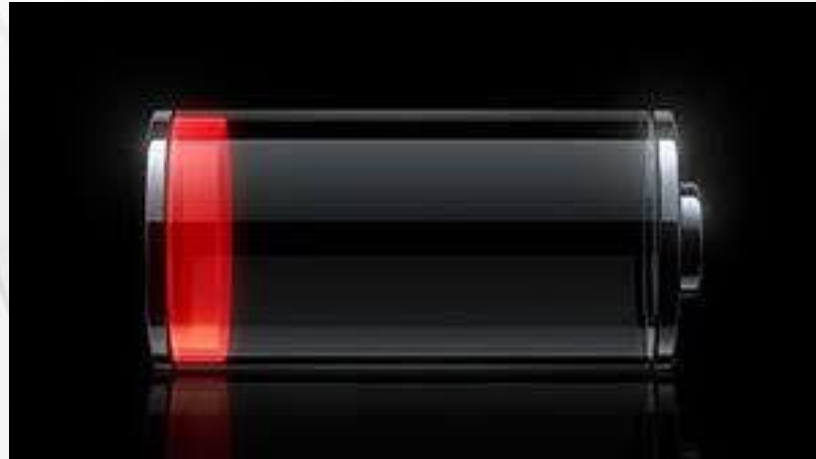
# ENERGY KICKS

---

Kevin Shah, Nur Nibir, Kahlil Francis,  
Joshua Boniuk

# The Problem

- The poor battery life of todays mobile devices



# Background Information

- The average person walks 1000 – 5000 steps a day
- New York City walkers log an average of 7000 – 8000 steps a day

# Mission

*Charging electronic devices by harvesting kinetic energy*

# Inspiration



A Dynamo Torch was used as the model for the Sole Power shoes.



# Physics

- Voltage = Current x Resistance
- Capacitance Formula -  $C=Q/V$
- Voltage from phone charger - 5V
- Generator gives AC (Alternating Current)
- Phones require DC (Direct Current)



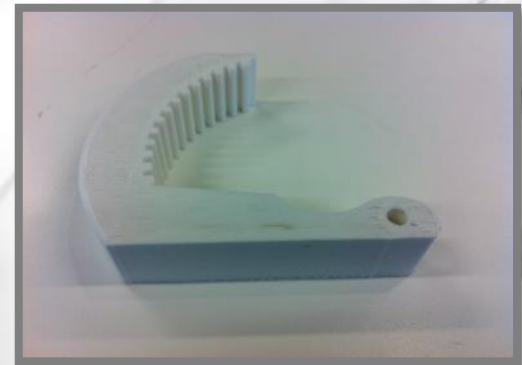
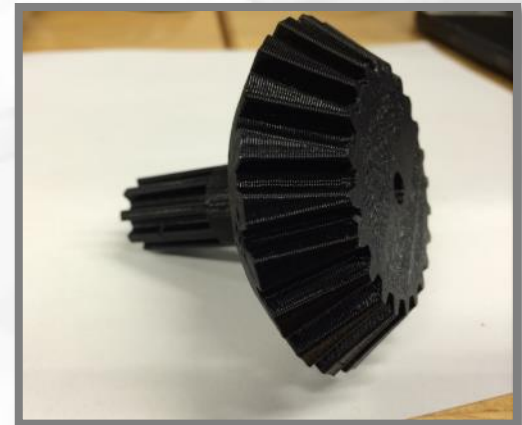
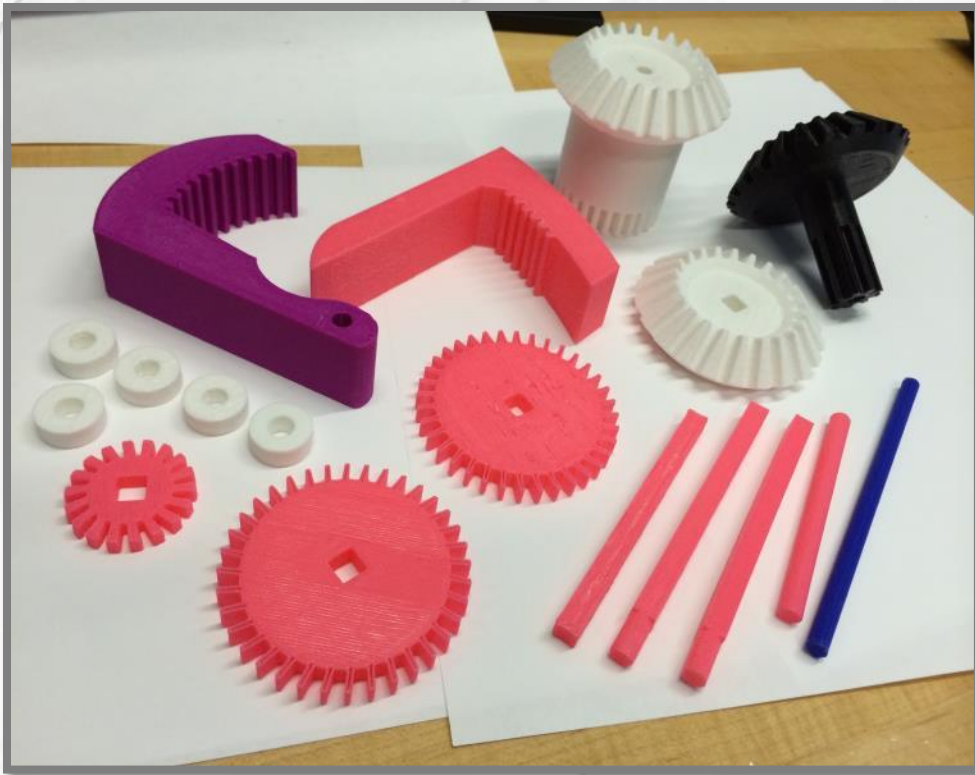
# Process

## AutoCAD Inventor

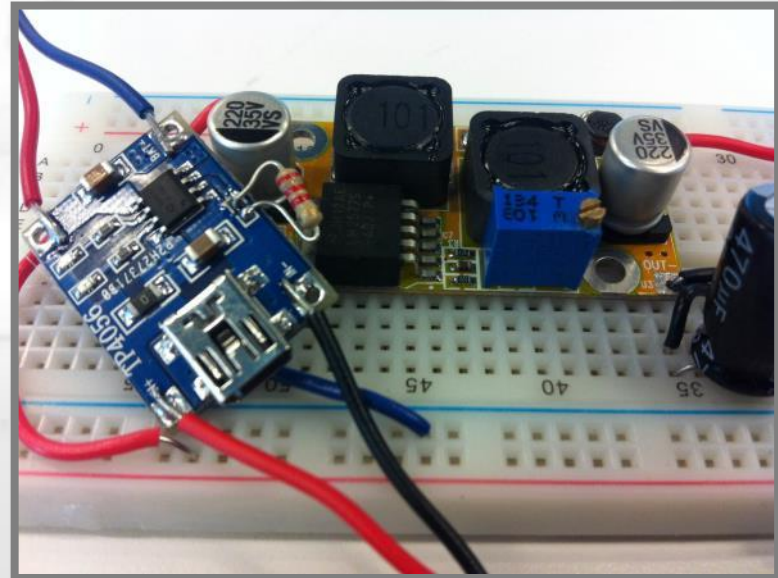
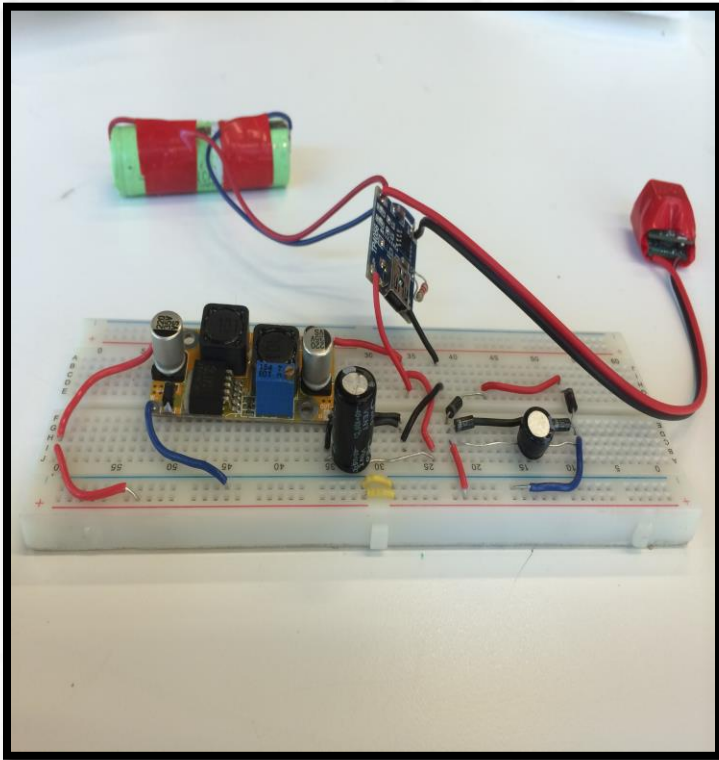




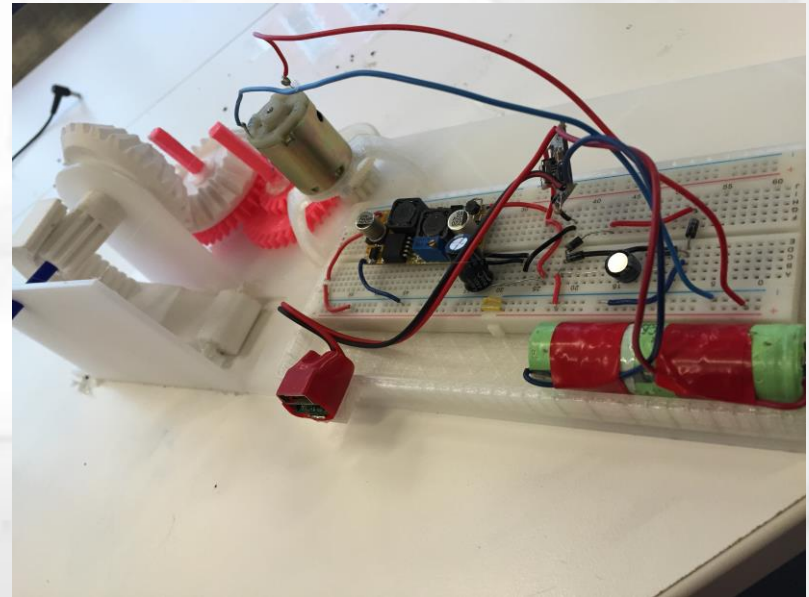
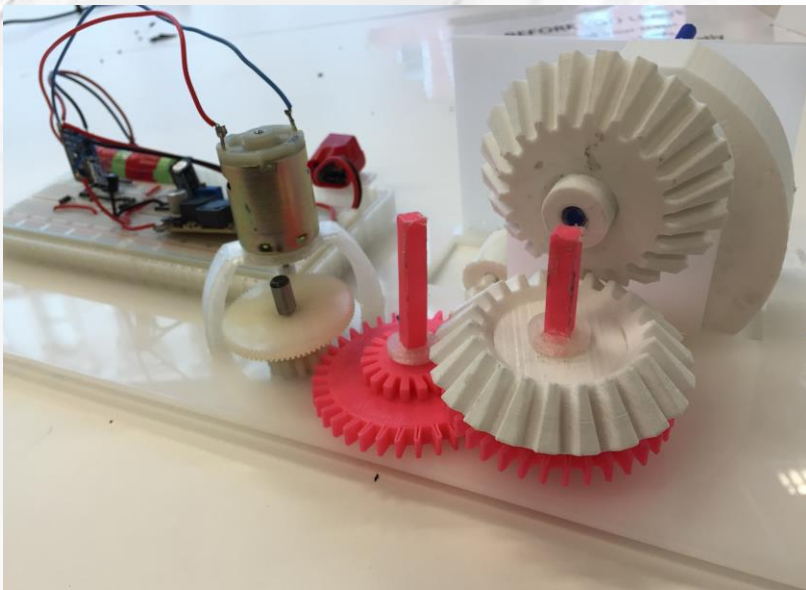
# 3D Printing



# Hardware

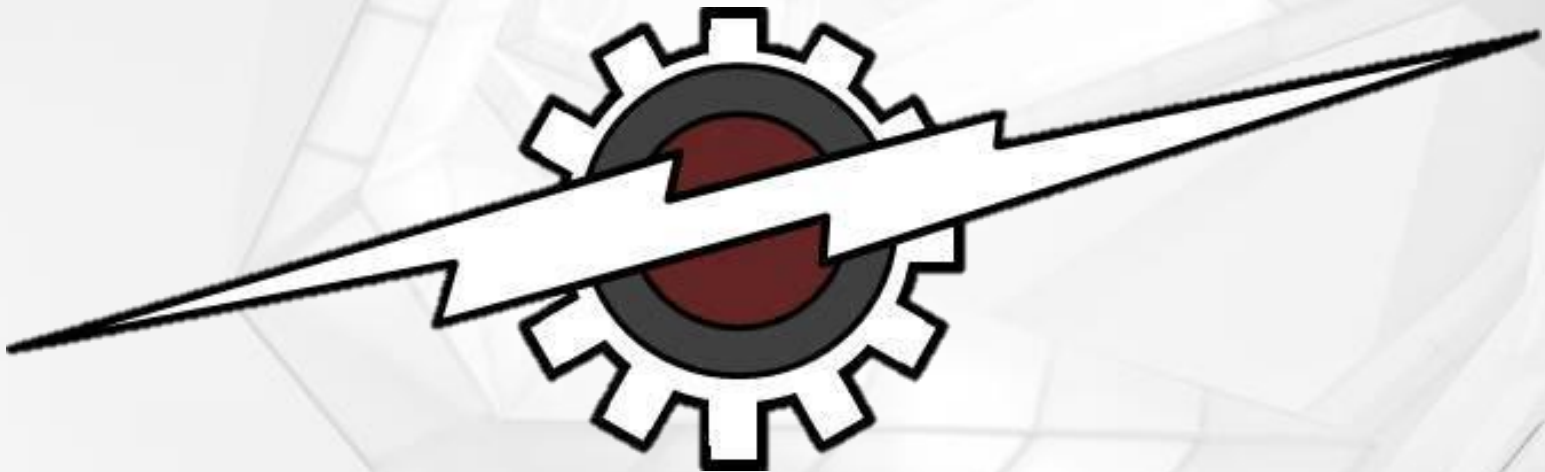


# Future Work



The next goal is to condense the project so that it fits into the sole of a shoe.

# Conclusion



Energy Kicks will revolutionize the way people charge their mobile devices in the modern era.

[EnergyKicks.Wordpress.com](http://EnergyKicks.Wordpress.com)





# THE ANXIETY AVENGERS

---

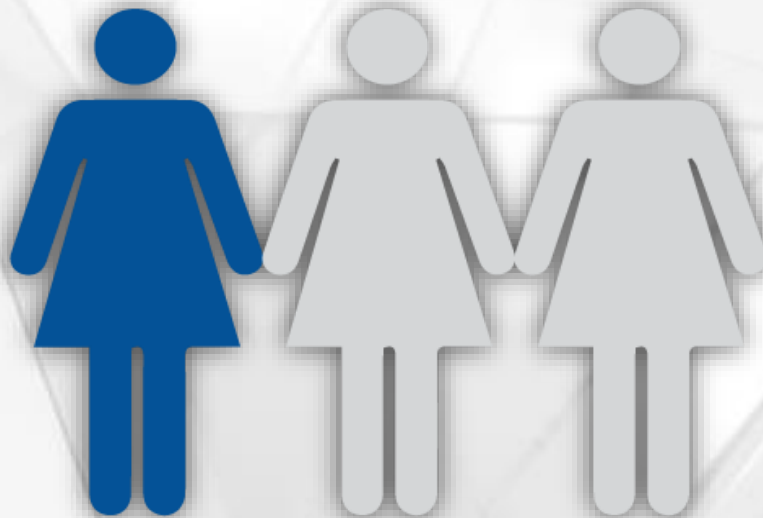
Jules Almazar, Iearys Fernandez,  
Valerie Ivanov, Ayesha Haniff



Anxiety consists  
of excessive  
worry that the  
person cannot  
control.

# Introduction

- **40 million** adults are affected (**18%** of the US population)
- Only **1/3** of the population receives proper treatment





# Introduction

Anxiety develops from complex factors including:

- Biological
- Environmental
- Life Events

# What is our Goal?

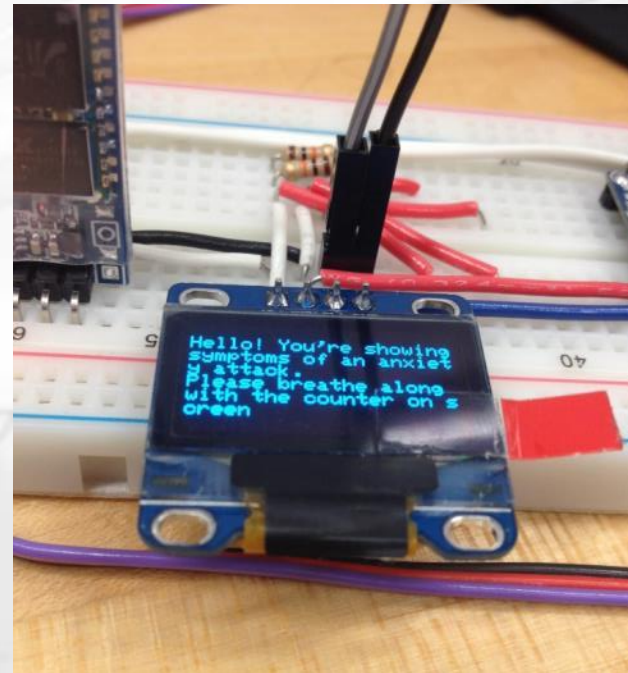


# Software

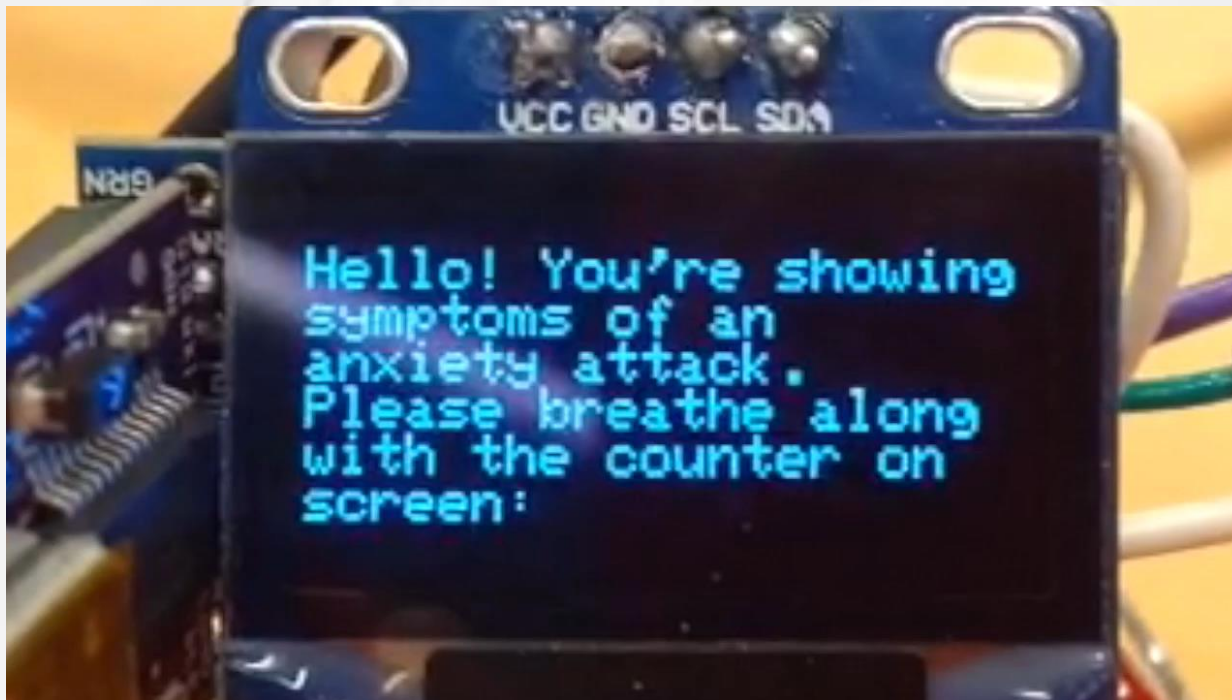
- There are 5 different codes
  - Pulse Rate
  - Body Temperature
  - GSR (Galvanic Skin Response)
  - Vibration Motor
  - OLED & RetroWatch

# Work Completed

- Pulse sensor
- Vibration motor
- Contactless temperature sensor
- OLED displays messages
- GSR



# Work Completed



# Finished Product





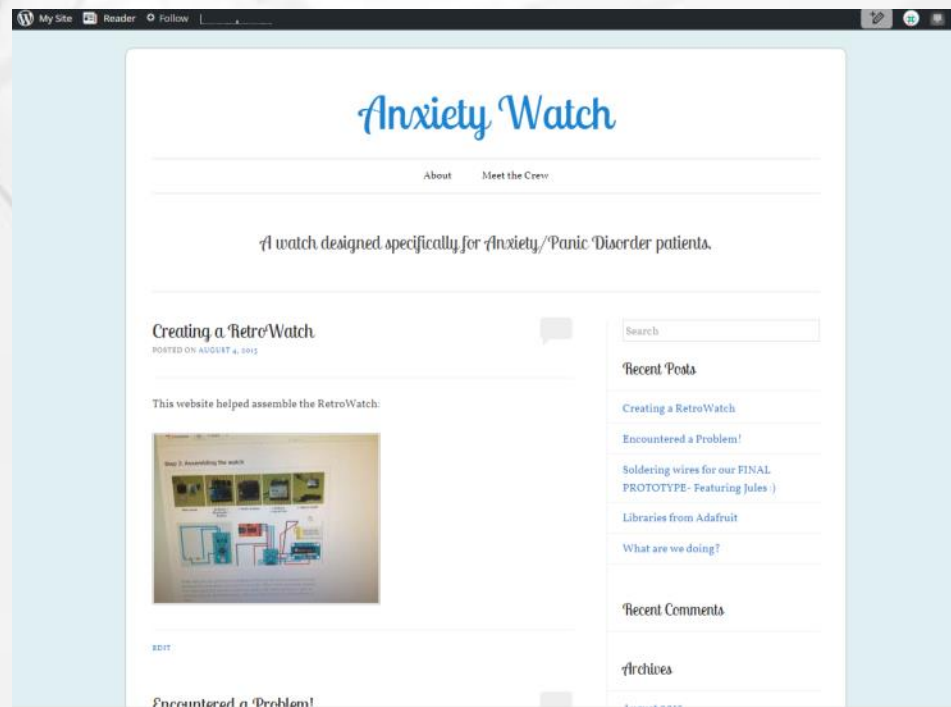
# Future Work

- App
- Testing
- Design
- Licensing



# Conclusion

- Our work will be monitored on our blog:
  - <https://anxietywatch.wordpress.com/>





# H.E.L.P. DRONE

---

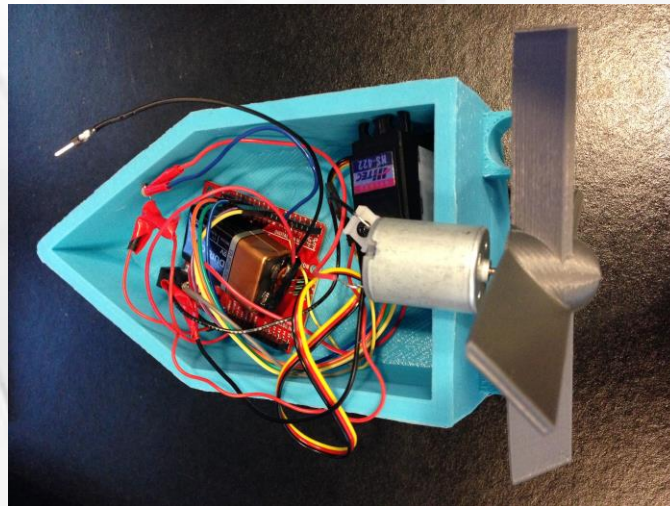
Lauren Raynor, Yash Balaji, Dylan Kennedy, Paulo Serodio

# Problems with Current Techniques



# Introduction

- Aim: To create a boat drone that delivers life preservers to drowning individuals

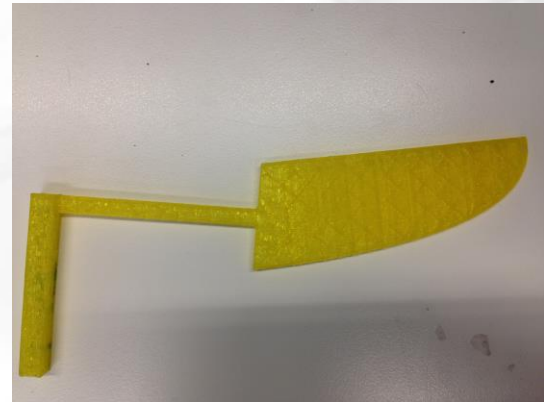
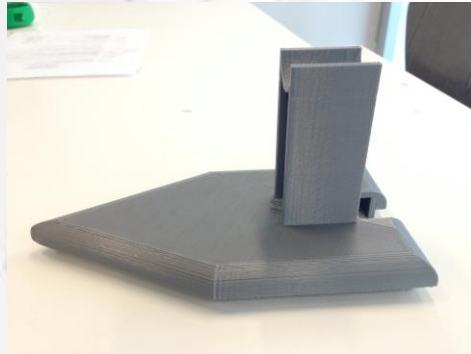


# RC Navigation

- Nordic nRF 24L01+
  - The switches control functions on the boat
  - The alarm goes off when the sensor sends a signal
  - <https://youtu.be/S249iorQMIE>

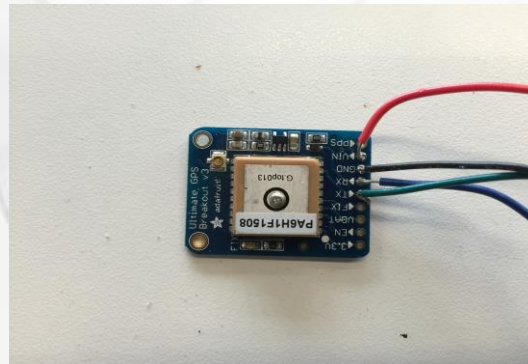


# Boat Design



# Future Plans

- Improve stability
- Implement a GPS navigation system
- Redesign wristband





# Conclusion

[www.helpdrone.weebly.com](http://www.helpdrone.weebly.com)



# EXO-HAND

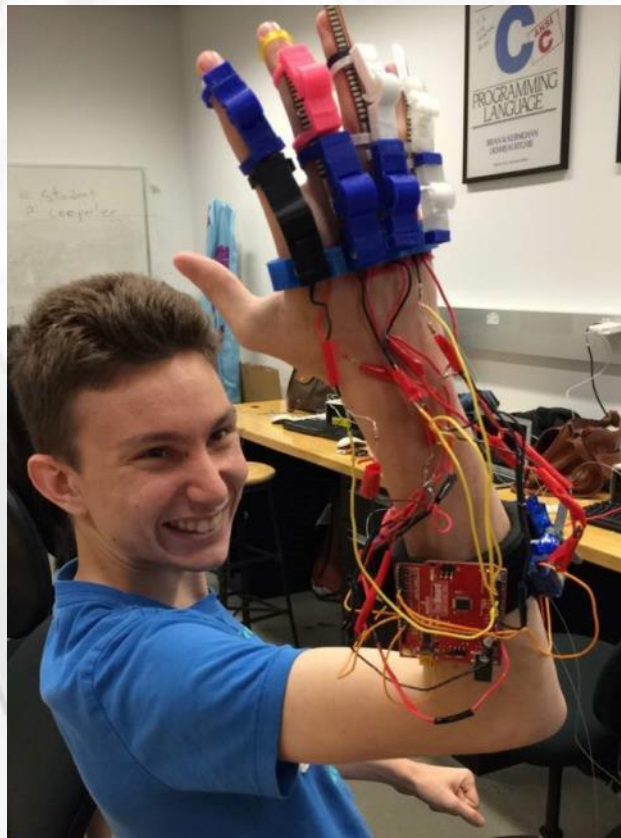
---

Tess Chan, Daniel Drucker, Max  
Miloslavsky, James Ng

# Problem

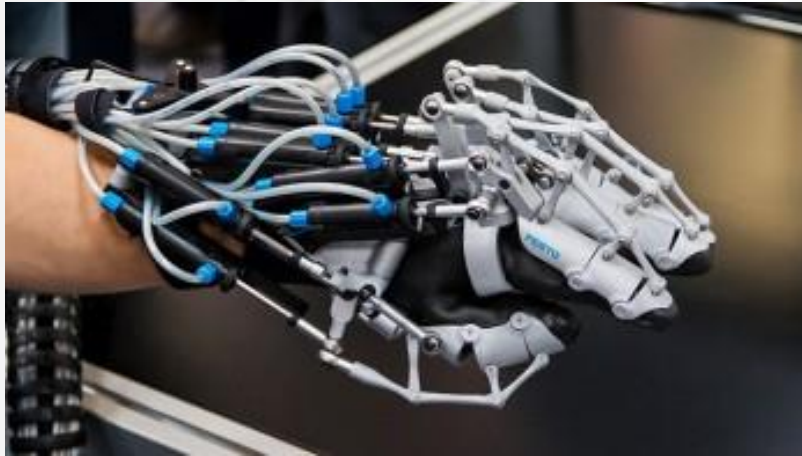


# Solution



# Background Information

Exoskeleton Hand



Servo Motor



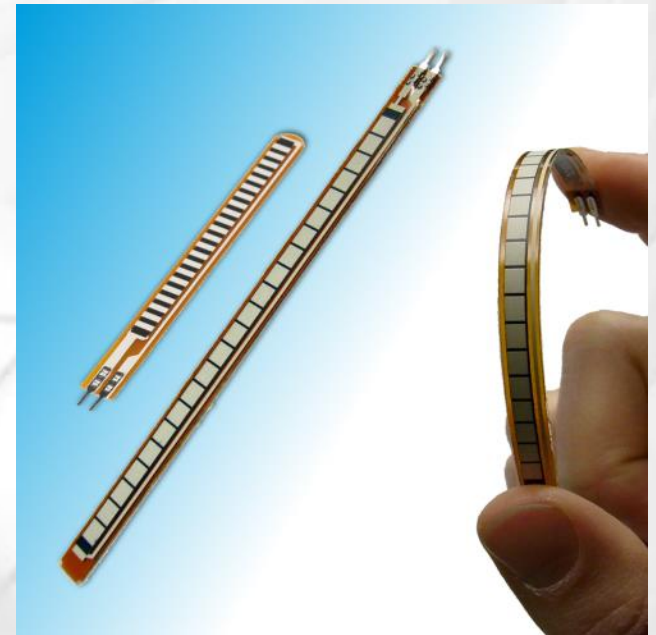


# Background Information

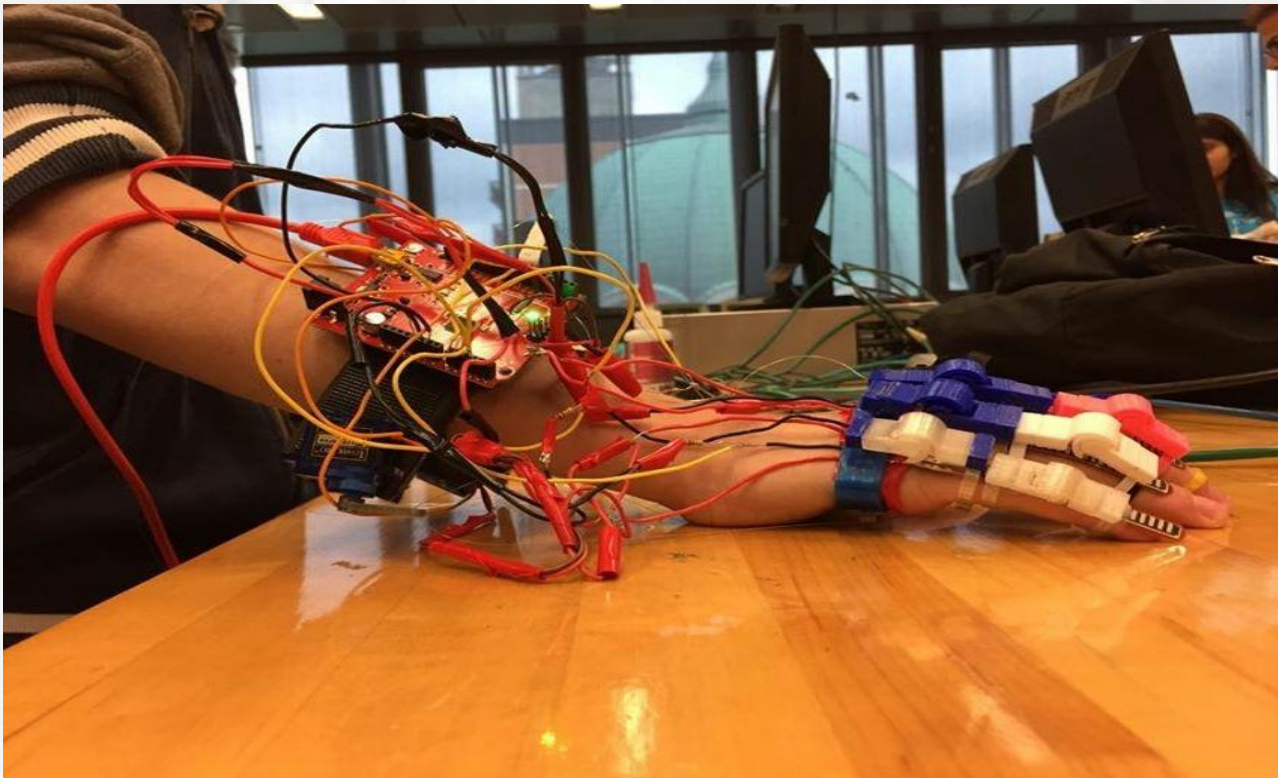
Finger Joints



Flex Sensors

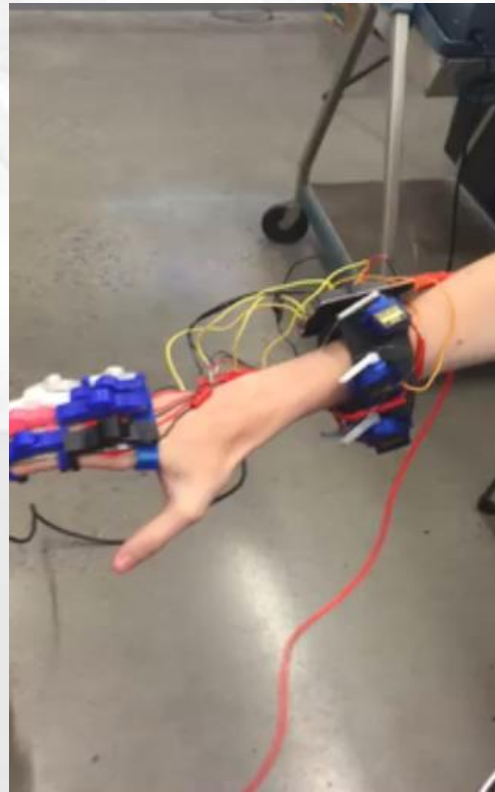


# Hardware





# Hardware Demonstration



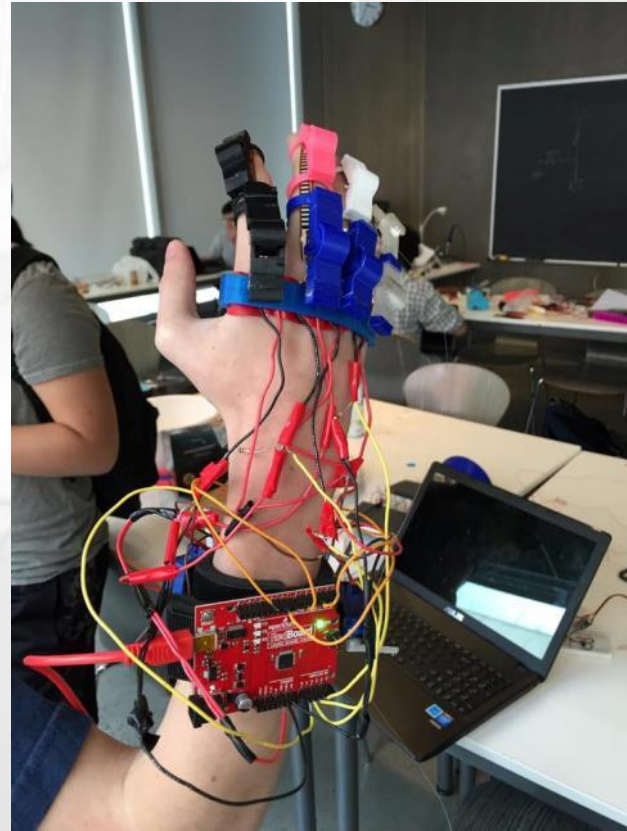
# Software

1. Initializes the position of the servo motors
2. Checks if any finger is moving
3. Exaggerates the finger's movement using the servo motor

# Conclusion

- A **handy** helper
- Inexpensive
- Large impact

Check out our work on:  
[myexohand.wordpress.com](http://myexohand.wordpress.com)



Ideally





# SEAHAWK

The amphibious bicopter.

---

Nina Bhardwaj, Wilfredo Cueto,  
Sommer Schneller, Rayhan Syed

# Introduction

Hobbyists spend significant amounts of money per year on R/Cs and drones that perform on only one terrain.



# Problem

**\$362.24**

The average cost of buying both an R/C drone and an R/C boat



# Solution

- What are we trying to accomplish?
  - Provide dedicated hobbyists with a cost-effective, multiple terrain vehicle.

# Solution

An amphibious bicopter with the capabilities of both flight and nautical exploration.

# Background Information



RPM



Servo Motors



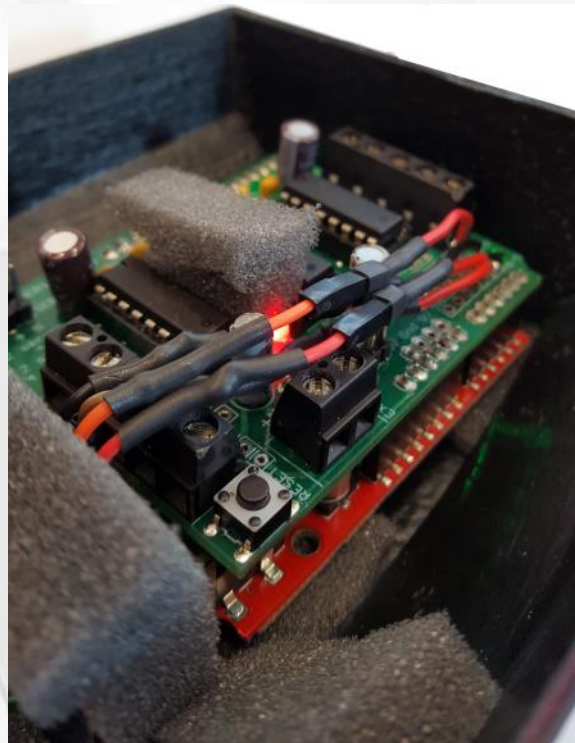
Software/Hardware



Waterproofing



Battery Supply



```

#include <Wire.h>
// #include <SparkFun_MMA8452Q.h>
#include <AFMotor.h>
#include <Servo.h>
// #include <SerialDebug.h>

// #define DEBUG true

AF_DCMotor motor1(1, MOTOR12_64KHZ);
AF_DCMotor motor4(4, MOTOR34_64KHZ);

Servo myservo1;
Servo myservo2;
int pos = 0;
// MMA8452Q accel;

void setup() {
  Serial.begin(9600);
  while (! Serial);
  Serial.println("Speed S0 to S255");
  Serial.println("Angle A0 to A180");
  // Serial.println("ACCEL Data begin ");
  myservo1.attach(9);
  myservo2.attach(10);
  // accel.init(SCALE_8G, ODR_800);

```

```

void printAccels()
{
  Serial.print(accel.x, 3);
  Serial.print("\t");
  Serial.print(accel.y, 3);
  Serial.print("\t");
  Serial.print(accel.z, 3);
  Serial.print("\t");
}

void printCalculatedAccels()
{
  Serial.print(accel.cx, 3);
  Serial.print("\t");
  Serial.print(accel.cy, 3);
  Serial.print("\t");
  Serial.print(accel.cz, 3);
  Serial.print("\t");
}

void printOrientation()
{
  byte pl = accel.readPL();
  switch (pl)
  {
    case PORTRAIT_U:
      Serial.print("Portrait Up");
      break;
    case PORTRAIT_D:
      Serial.print("Portrait Down");
      break;
    case LANDSCAPE_R:
      Serial.print("Landscape Right");
      break;
    case LANDSCAPE_L:
      Serial.print("Landscape Left");
      break;
    case LOCKOUT:
      Serial.print("Flat");
      break;

```

```

    if (Serial.available())
    {
      if (Serial.peek() == 'S') {
        int speed = Serial.parseInt();
        if (speed >= 0 && speed <= 255)
        {
          Serial.println(speed);

          motor1.run(FORWARD);
          motor1.setSpeed(speed);

          motor4.run(FORWARD);
          motor4.setSpeed(speed);
        }
      }
    }
  else {
    int pos = Serial.parseInt();
    if (pos >= 0 && pos <= 180)
    {
      myservo1.write(pos);
      myservo2.write(pos);
      Serial.println(pos);
    }

```

Brainstorming  
possible  
methods of  
production



Modeling with  
3D printer and  
on paper



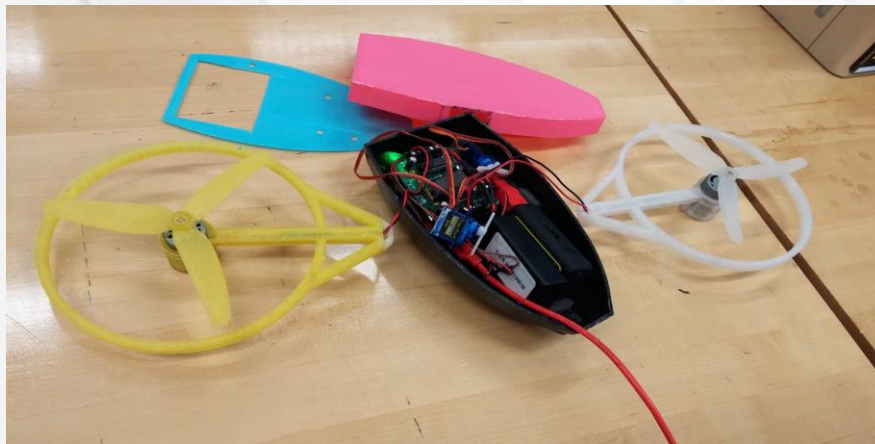
Begin coding  
arduino with  
redboard



3D printing and  
testing of parts  
with other parts



Hardware and  
software  
integration





# Future Work

- Integrate camera
- Add ground capabilities



[wix.com/sschneller1/seahawk](http://wix.com/sschneller1/seahawk)



# SOULRUNNER6

---

Ashley Gonzabay, Aditya Nadkarni,  
Jon Nelson, Joanne Park, Lindsey  
Tarpinian



# Introduction

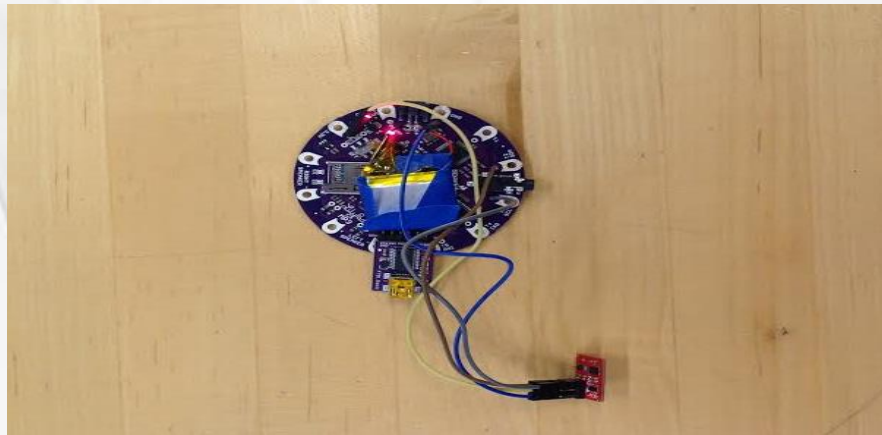
- Purpose of invention
  - To change the song an individual is listening to according to his or her pace
- Goals
  - To create a wearable independent of a cellular device for an enjoyable workout

# Background Information

- C++ syntax in Arduino
- Accelerometer, SD card and Lilypad MP3 libraries
- Wire libraries
  - Data transport
- Vector formula: magnitude of the X,Y,Z coordinates

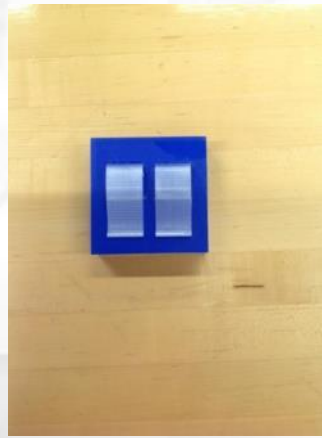
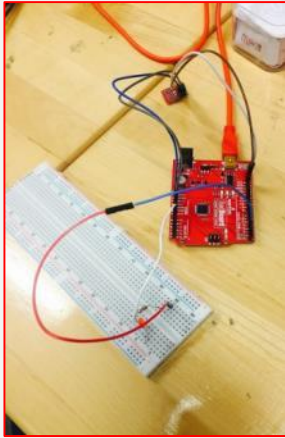
# Work Completed

- Used accelerometer sensor and tested values
- Wrote algorithm to measure time between each step
- Connected accelerometer to Lilypad MP3
- Wrote code to play songs according to pace using BPM

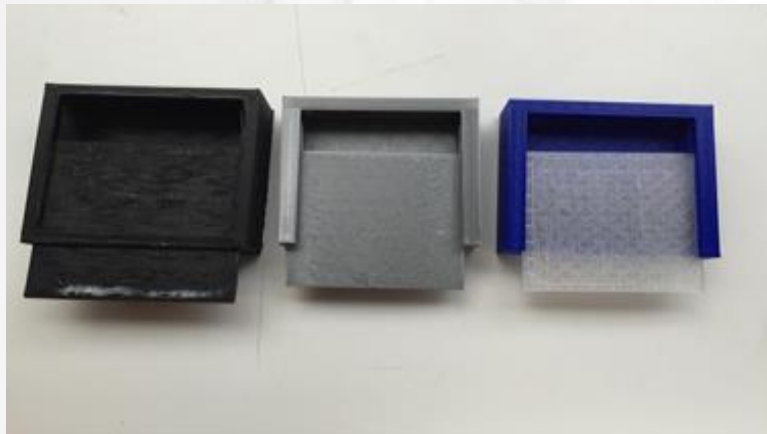




# Prototypes



# Prototypes

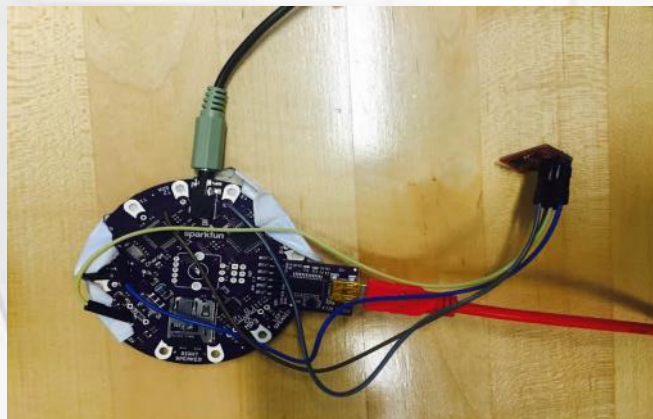


# Future Plans

- A waterproof casing to prevent damage
- A Bluetooth function that will allow a runner to upload their own playlist
- A smaller version of the prototype

# Conclusion

- Determined time between steps
- Hooked up accelerometer to a Lilypad MP3 board and got the accelerometer to sense movement and vibrations
- Successfully changed songs based on runner's pace





# MY AIR

---

Tae Kyung Kong (TK), Ian Murray,  
Nellie Spektor, Callista Ohnemus



MY AIR



# The Problem

*There is more than air out there.*



**On a Scale of 0 to 500, Beijing's Air Quality Tops 'Crazy Bad' at 755 - NY TIMES (2013)**



**Smog Filling Up New York City's Atmosphere**



THE COOPER UNION

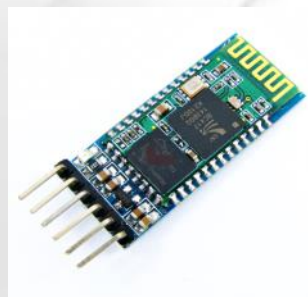
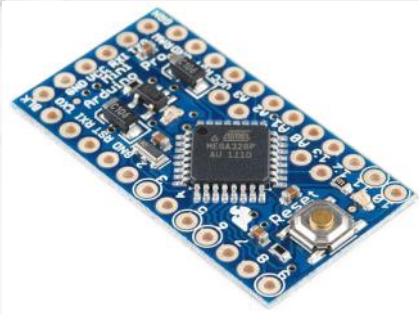
# The Solution

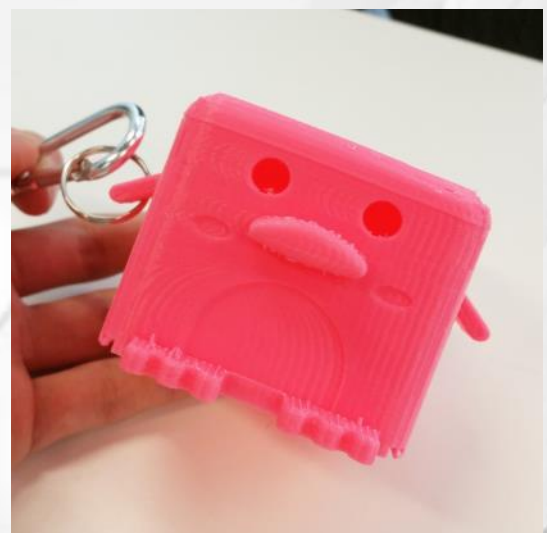
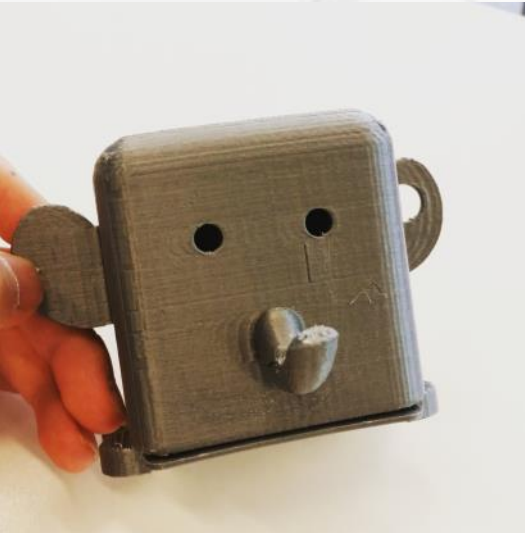
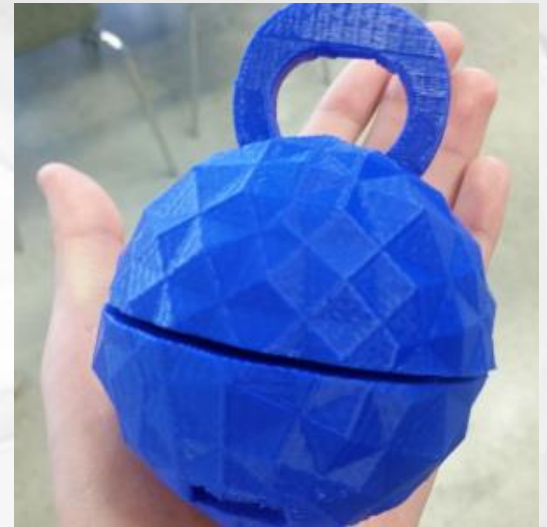
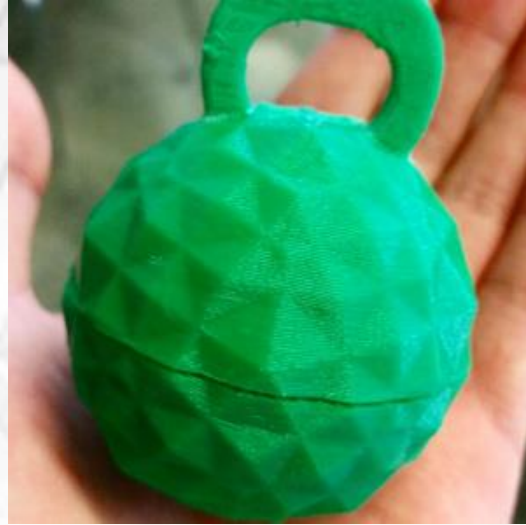
*There is more than air out there.*

*A portable device that is connected to a mobile application.*



# Materials

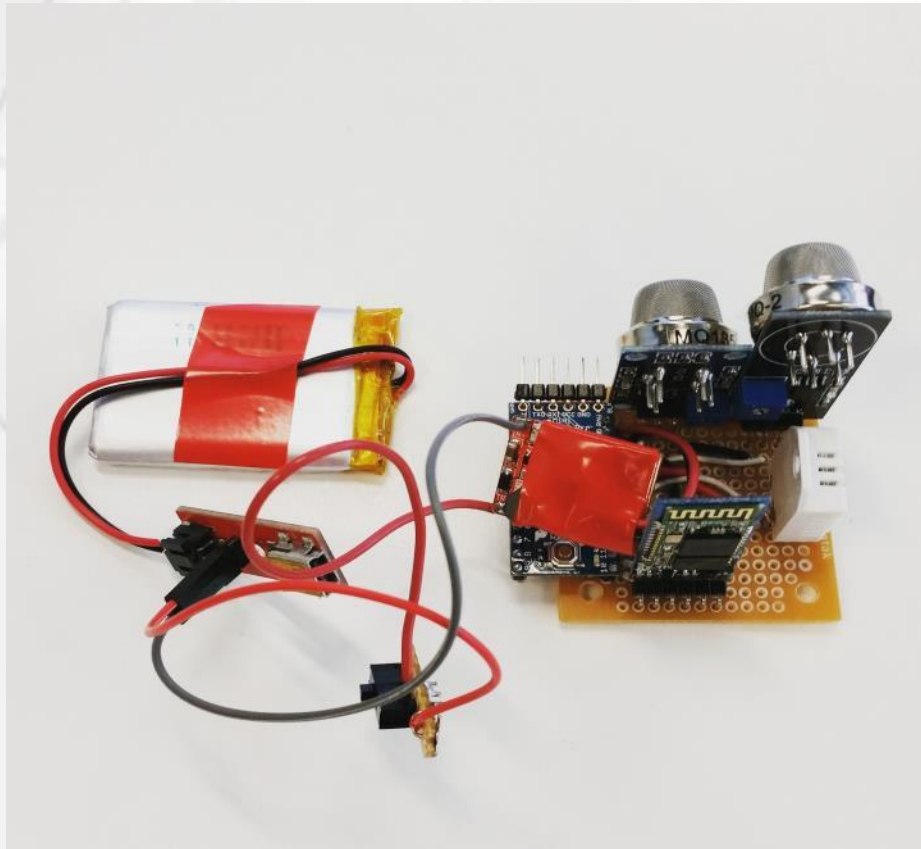




THE COOPER UNION



# The Circuit



# Android App

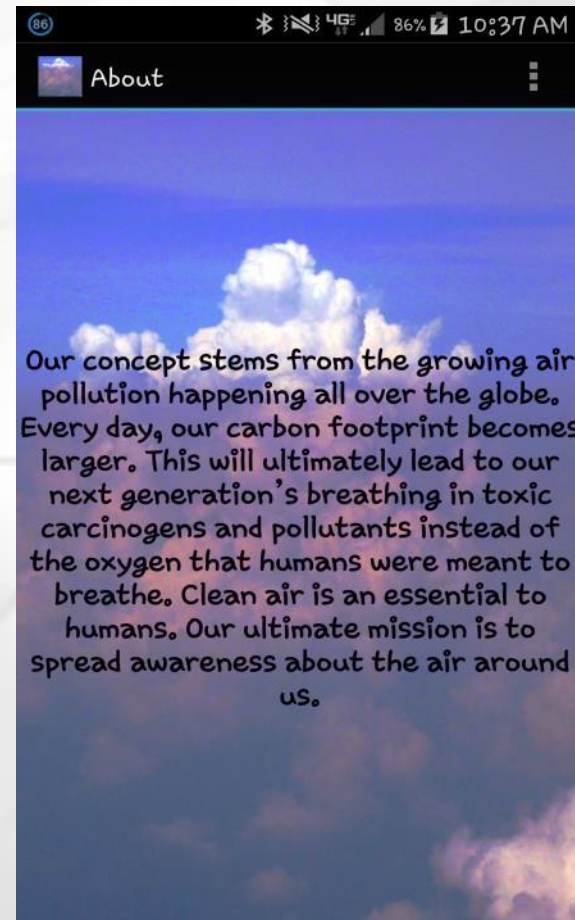




# Android App



# Android App



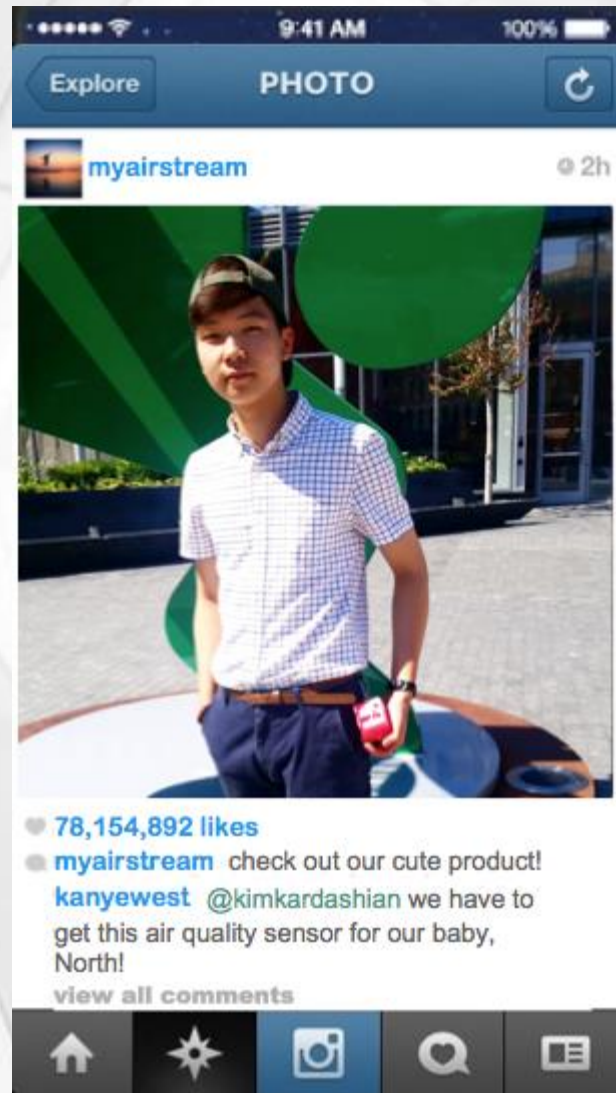
# Test Data



# Future Plans

- Smaller
- Cheaper
- ThingSpeak
- Multiple Cases for User's Preference







# THE OMNISHOE

---

Darren Lin, Michelle Nissan, Shane  
Ngai, Patrick Schutz



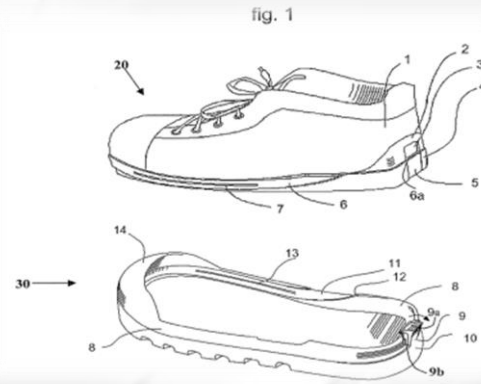
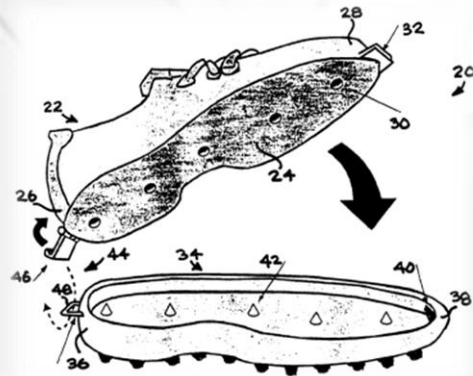
# Introduction

- Why are we doing this?
  - Alleviates the effect of shoe drag
  - Cheap Alternative to Buying Shoes
  - Very Student-Athlete friendly

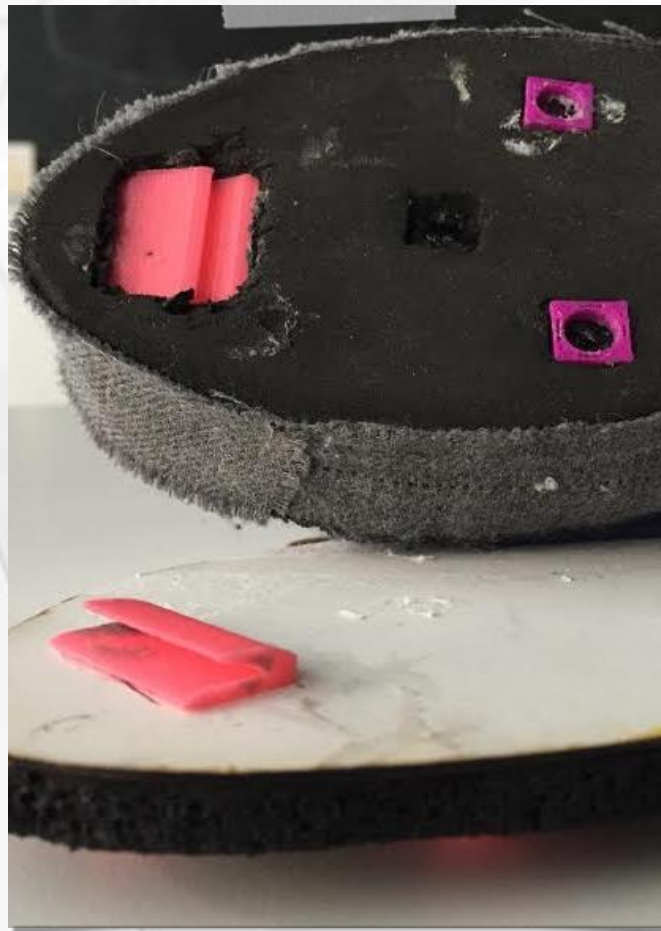


# Background Information

- Faults in past patents [6]
- Potential customer saving



# The Sole Swap System



# How to Put it Together



# Materials

- Anti-vibration rubber
- Structural card stock base
- Foam insoles for comfort



# Work Completed

- Two swappable soles
- 3L locking system
- Remade for pro-comfort/stability



# Future Aspirations

- Make our product fashionable
- Make more specialized soles
- Perfect our sole swap system



# T<sub>echnical</sub> I<sub>ndoor</sub> P<sub>ositioning</sub> S<sub>ystem</sub>

---

Hoi Kwan, Sherry Wang, Kenny Yang,  
Dillon Zhang

# Introduction

IPS for Commercial Centers

- Locating User
- Providing Navigation Instructions

# Background

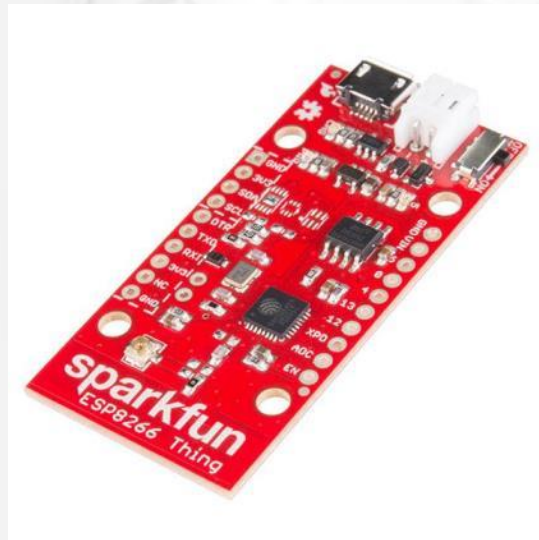
Google Maps (GPS)

iBeacon

Received Signal Strength Indication

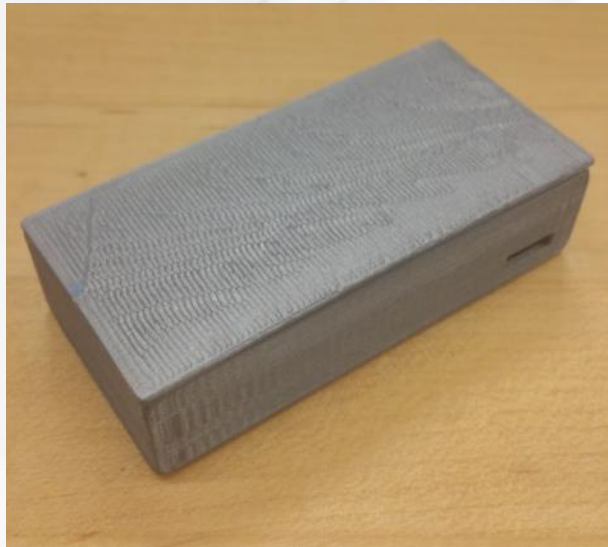
# Hardware

- ESP8266 Thing with a Lithium Ion Battery



# Hardware (cont)

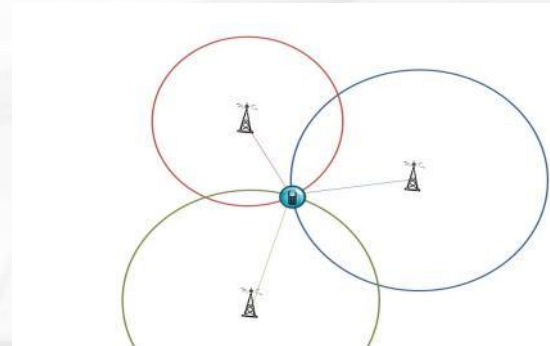
- 3D Printed Containment Units





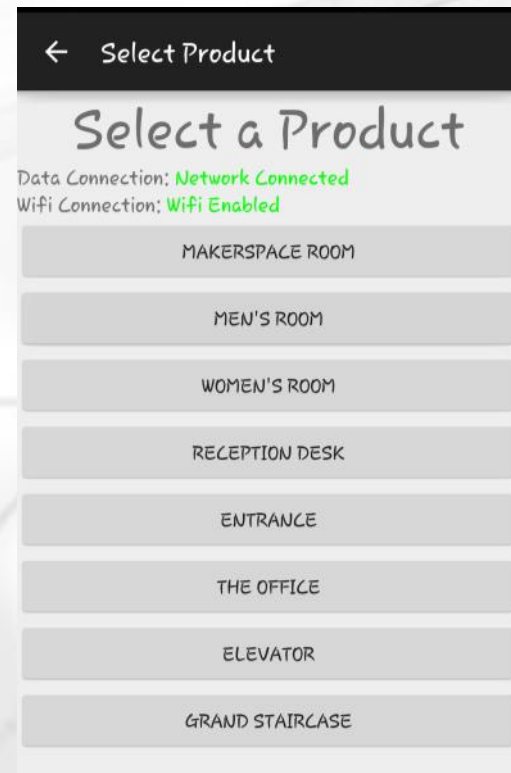
# Software

Triangulation of User



```
public static double calculateDistance(double levelInDb, double freqInMHz) {  
    double exp = (27.55 - (20 * Math.log10(freqInMHz)) + Math.abs(levelInDb)) / 20.0;  
    return Math.pow(10.0, exp);  
}
```

# Software (cont)



# Software (cont)

## A\* Search



# Conclusion





# TRAINTech PRESENTS LIGHTHOUSE

---

Jason Kurian, Michael Ye  
Yair Gross, Yash Jain





# Background Information

- 8,758,000 daily MTA passengers
- 954,000 daily NJ Transit passengers
- Over 3 billion annual riders use MTA transportation
- More people take the MTA daily than live in 37 of the 50 states.

Huge and Growing Available Market!

# Background Information

- Most people try to catch a nap on their commute
- Missing your stop is extremely frustrating and time consuming



Time is a commodity you can't get enough of!

# Product Design

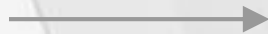
- Armband connected to app via Bluetooth
- App predicts where passenger is
- Built-in timetables determines arrival time
- Band vibrates moments before destination

# HARDWARE

# Hardware: Wristband



Continuous



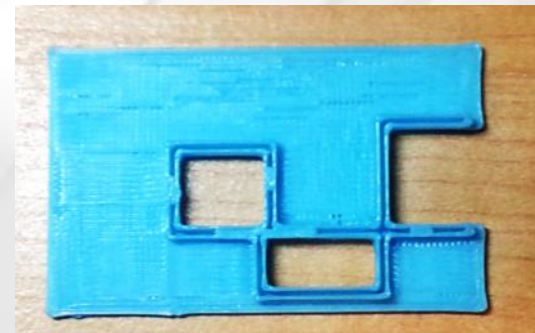
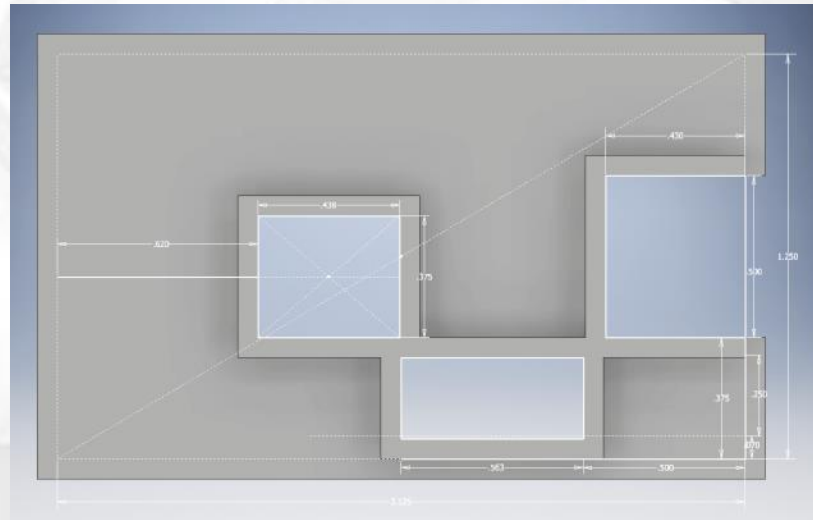
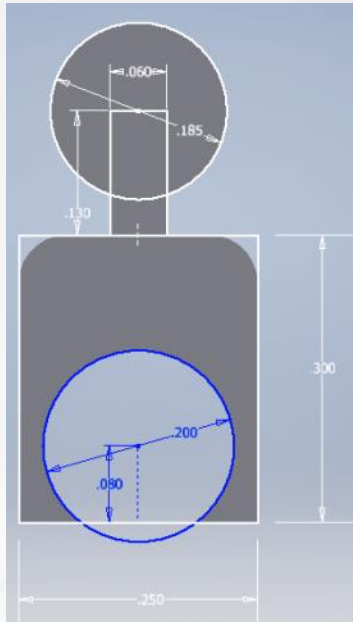
Clasp



Modular

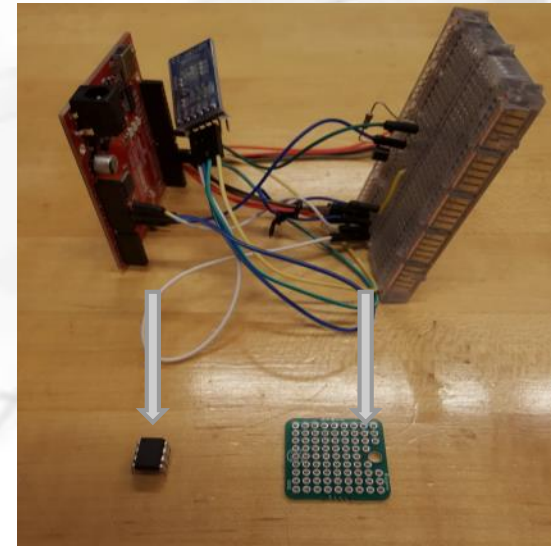


# Hardware: Wristband

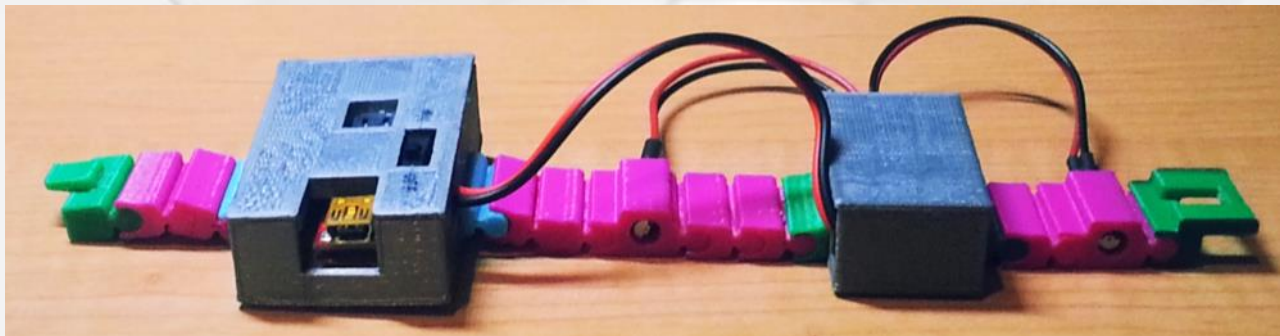
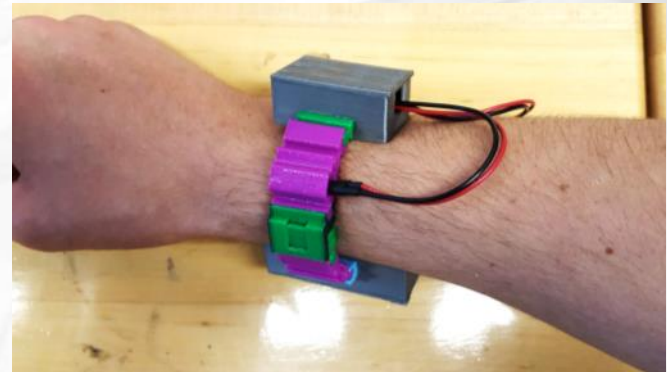
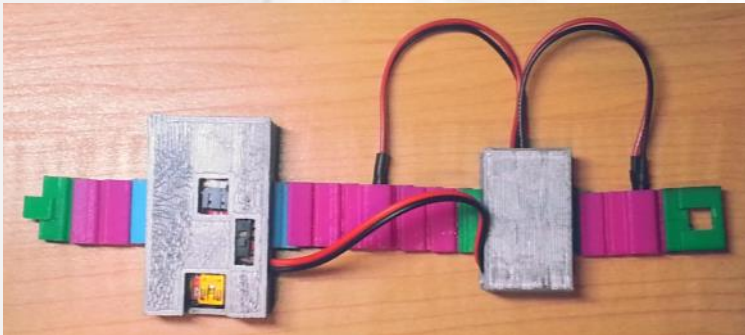


# Hardware: Circuit

1. Draw schematic
2. Build and test circuit
3. Minimize size using proto board and smaller components
4. Solder final circuit and integrate power source



# The Finished Wristband



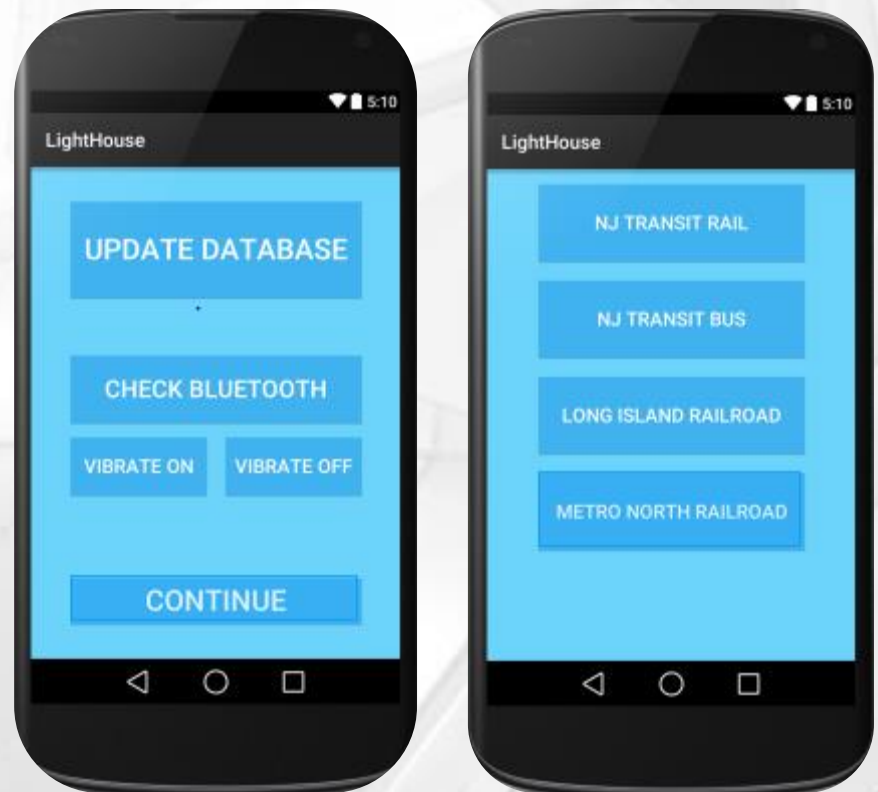
# Android App: User Interface

- Select transit system
- Select starting point/destination
- Select departure time
- Set alarm or pin to home screen



# Android App

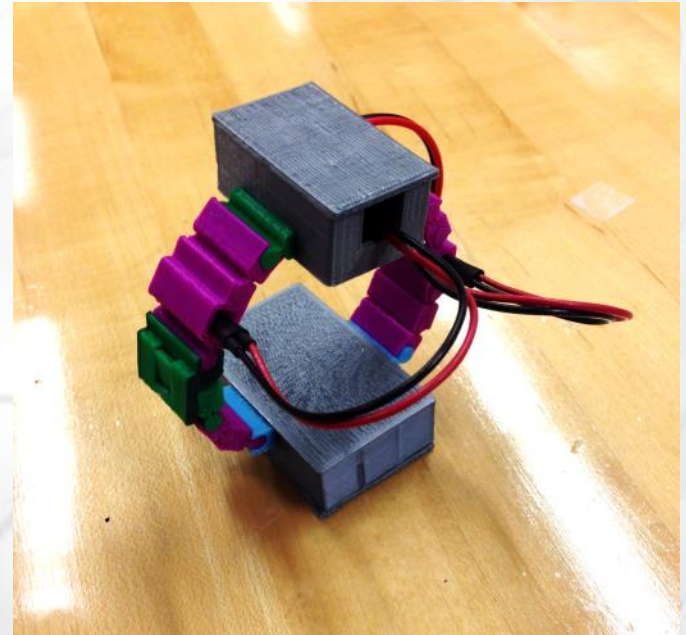
- SQLite database
- Internet-independent
- Bluetooth capability
- Simple interface





# Future Plans

- Real-time data
- Decrease battery size
- Expansion to all MTA Systems
- Circuitry built into individual links



# LightHouse

- Fresh
- Functional
- Fashionable
- Funky



[lighthousebraintech10.wordpress.com](http://lighthousebraintech10.wordpress.com)